

Dynamic Human-Centered Suit Design: A Computational and Experimental Method

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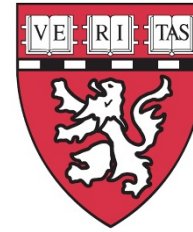
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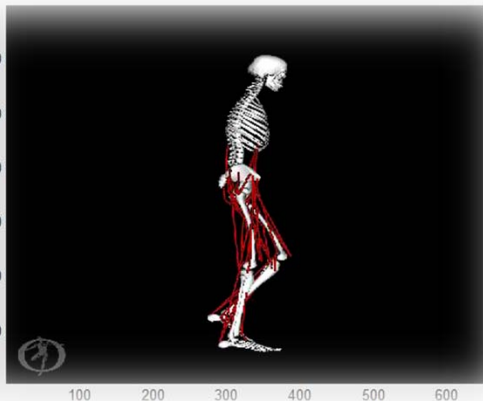
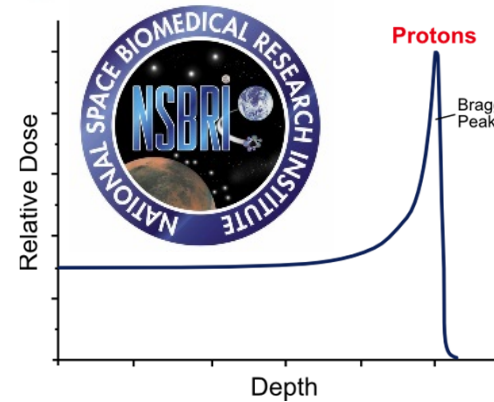
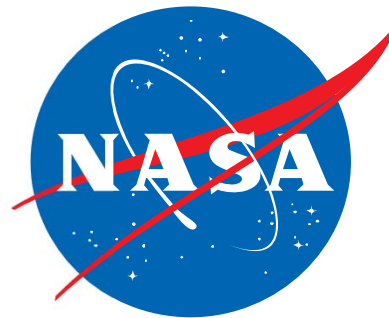
About Me



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Background

Why does NASA fund PSS mobility/agility research?



Objectives of Internship

- ❑ Research & compare possible software packages for an analysis pipeline
 - Musculoskeletal Modeling (OpenSim, AnyBody, LifeMOD, SANTOS)
 - CAD (AutoCAD, SolidWorks, ProE)
 - FEM (ANSYS, Creo2, Abaqus)
- ❑ Obtain current CAD representations of the hip joint assembly
- ❑ Develop the CAD representation to include high fidelity information
 - Obtain and input complete component characterizations
 - material characteristics, composition, weight
 - Determine and input bearing characteristics - Force-displacement (time variant curves)
 - Breakaway Force, steady state dynamics, and transitional dynamics
- ❑ Force plate gait test, fully suited, to obtain normal and shear force plate inputs for a musculoskeletal crewmember model

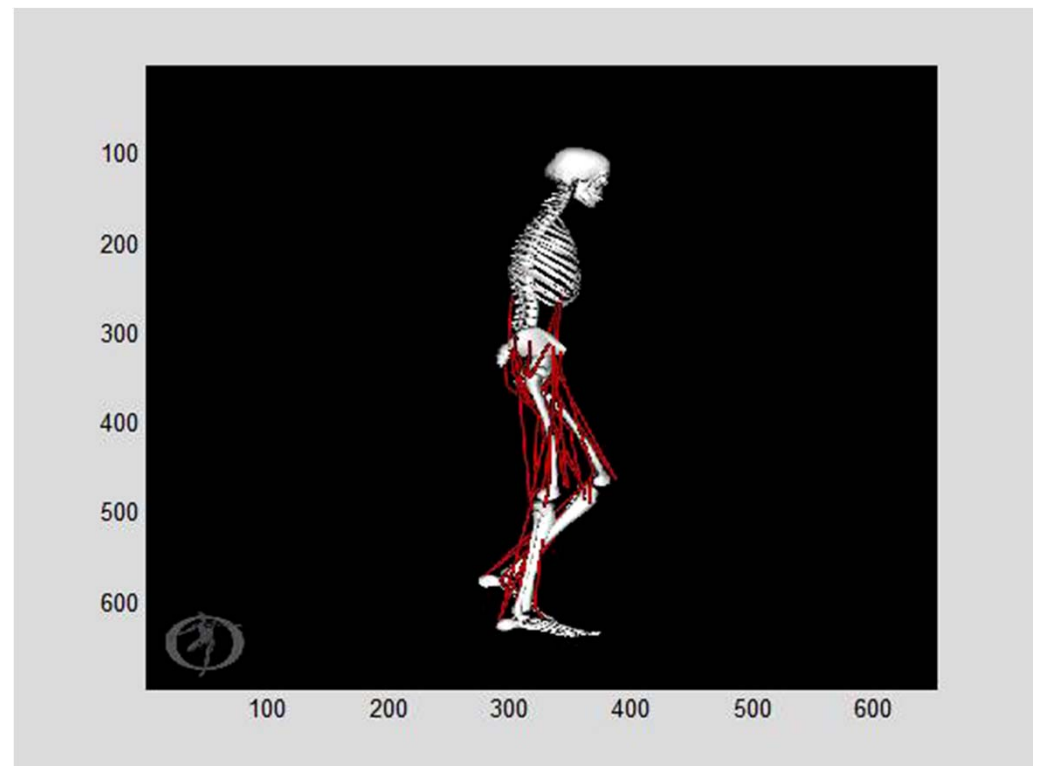
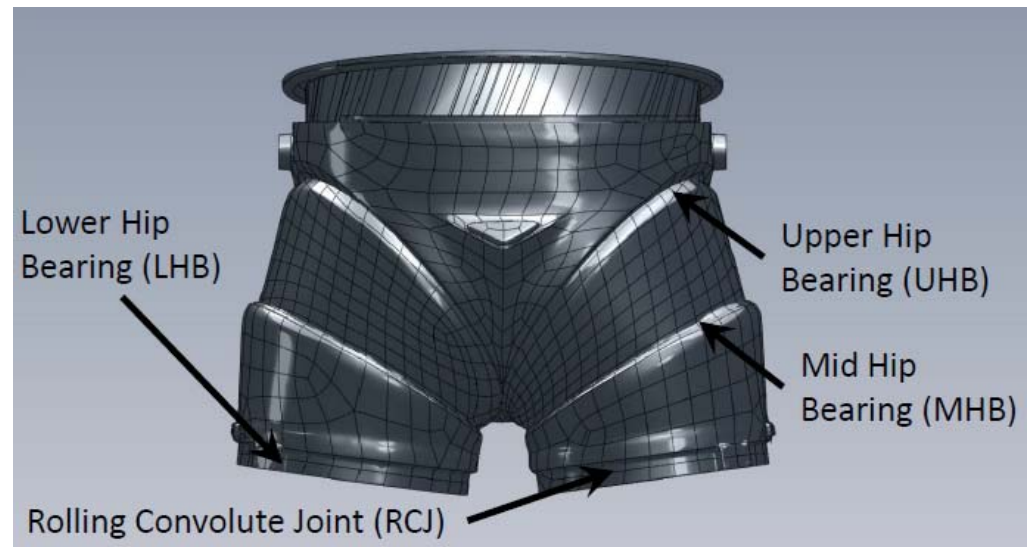
Methods/Procedures or Skills

❑ Geometry Details - Bearing Experiment

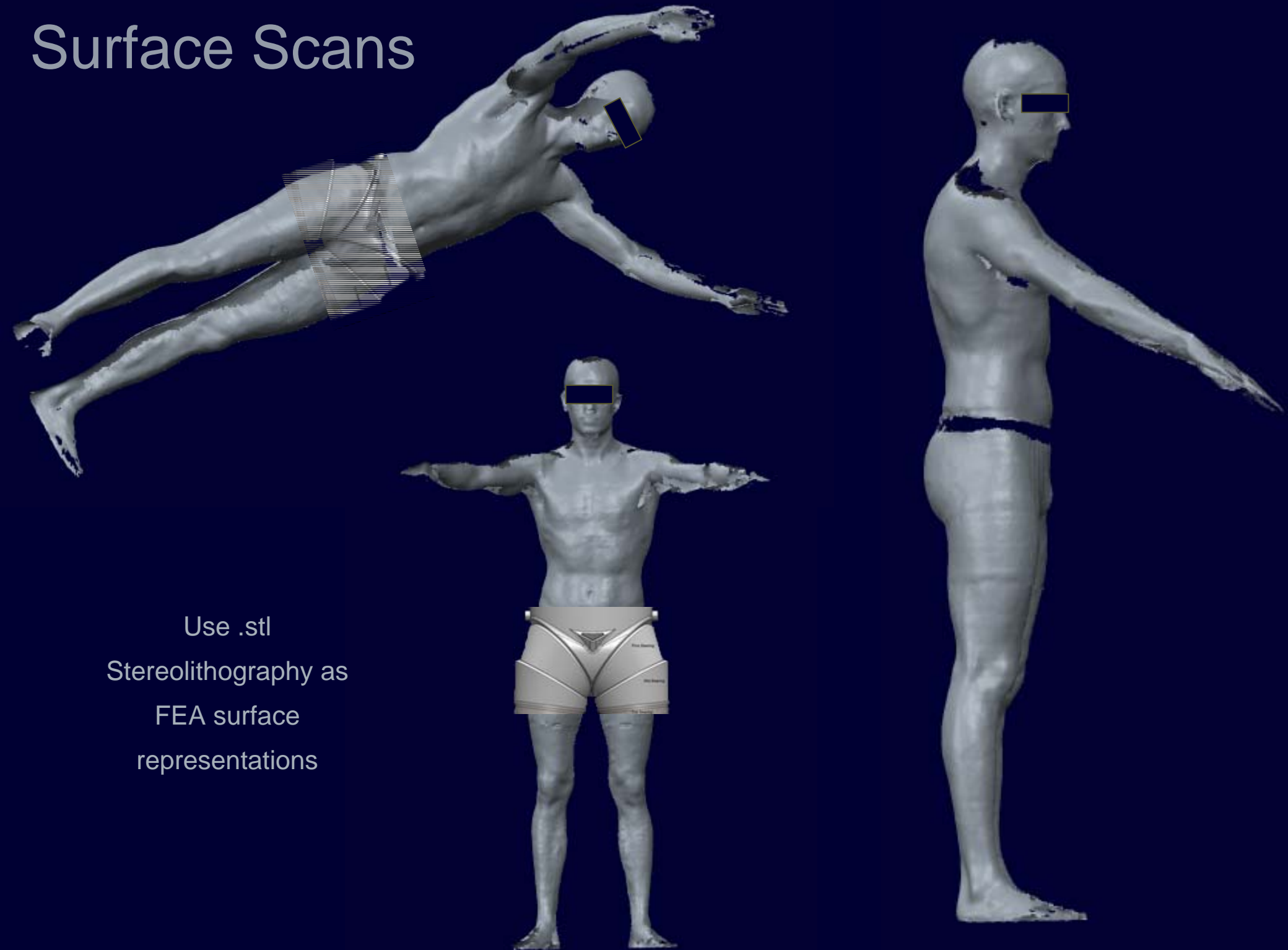
- Isolate Individual Bearing
- Dynamometer: Constant V or F
- Understand Response Profiles
- Repeat for Each Bearing, 1-Side

❑ Crewmember Details – Mobility/Agility Experiment

- Normal Gait: Suited vs. Unsuited
- GRF & ROM: 6DOF Force Plates & Vicon Motion Capture Systems
- Planetary Surface Motion: Kneel & Recover, Side Step, Walking Backwards



Surface Scans



Use .stl
Stereolithography as
FEA surface
representations

